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# Digitale Infrastructuur voor Toekomstbestendige Mobiliteit

**Beyond Roads: how the DITM project is  
contributing towards a digital infrastructure  
for future-proof mobility!**

Amsterdam, April 17



Funded by  
the European Union  
NextGenerationEU

**BRAINPORT DEVELOPMENT**  
economische ontwikkelingsmaatschappij

  
AUTOMOTIVE  
INDUSTRY NL

# Agenda

- Introduction of the DITM project
- Technology for higher levels of automation
  - Digital maps
  - Traffic management
- Usecases
- Transition Paths
- Q&A



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Digitale Infrastructuur voor Toekomstige Mobiliteit

16 May 2024

Goal: Enable higher levels of autonomous driving

Lead partner

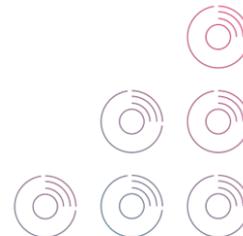
BRAINPORT DEVELOPMENT  
economische ontwikkelingsmaatschappij

20

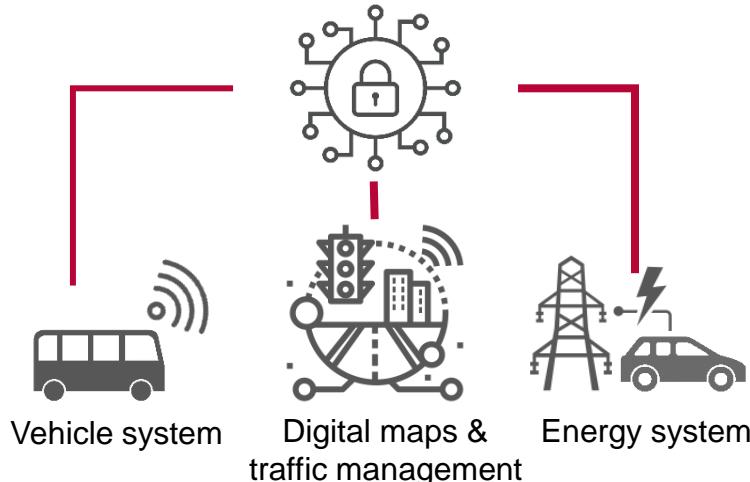
Partners

16

Companies



# Digitale Infrastructuur voor Toekomstbestendige Mobiliteit



€ 60 million



1 Oct 2022  
1 Oct 2026

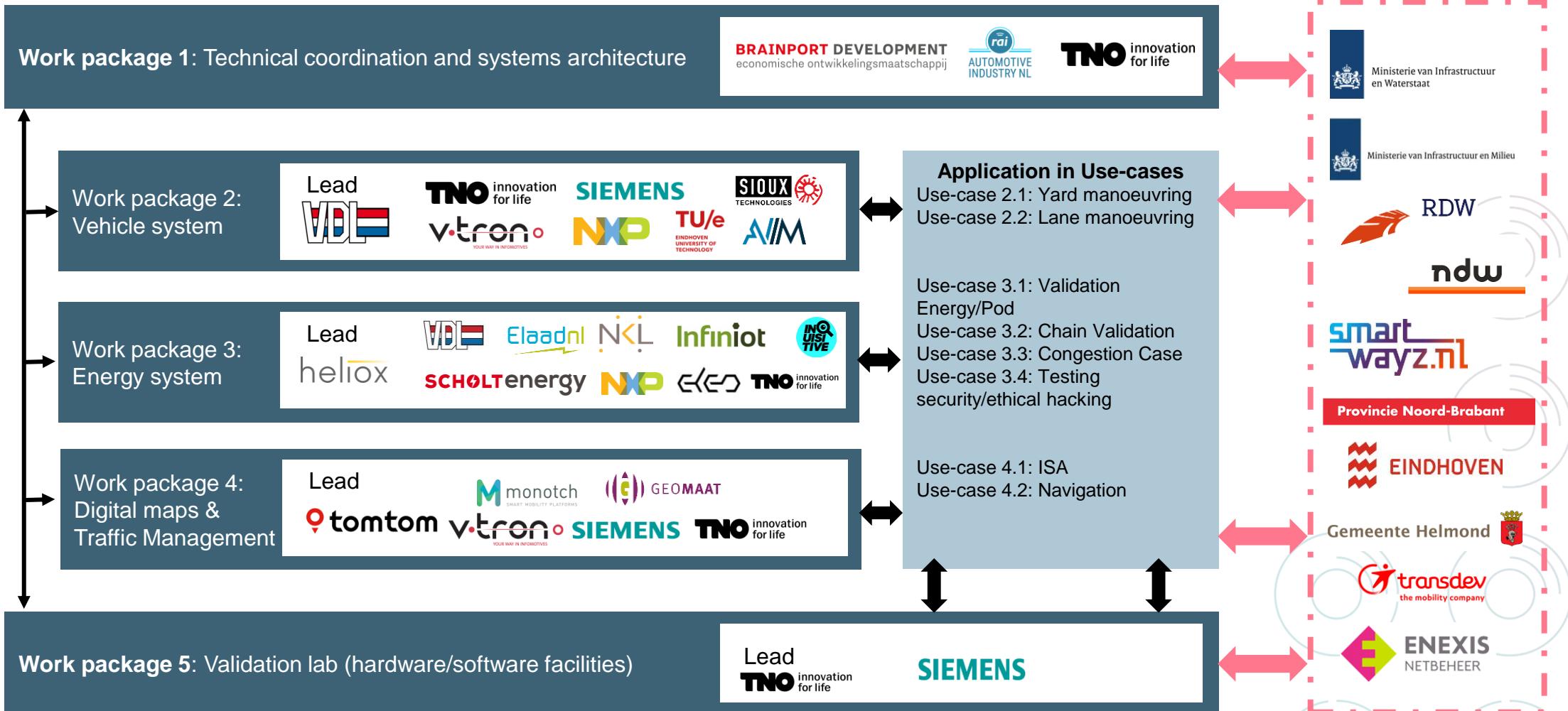


Website [link](#)

*"On the way towards full autonomous vehicles, we develop the underlying technologies for advanced driver assistance systems (ADAS) which provide the safe and increasingly autonomous experiences that will reshape our relationship to transport.- Brian de Bart, NXP*



# WP Overview



**Workpackage 4**  
**Digital maps and**  
**Traffic Management**

WP Leader



Data-sharing environment connecting to Automotive- and Big-Tech sectors (Overture)

Powering next generation Map- and Traffic management products from interoperable open map data shared between Private- and Public sectors

Data-sharing environment connecting to Realtime Road-authority data (TN-ITS, RTTI, ...)

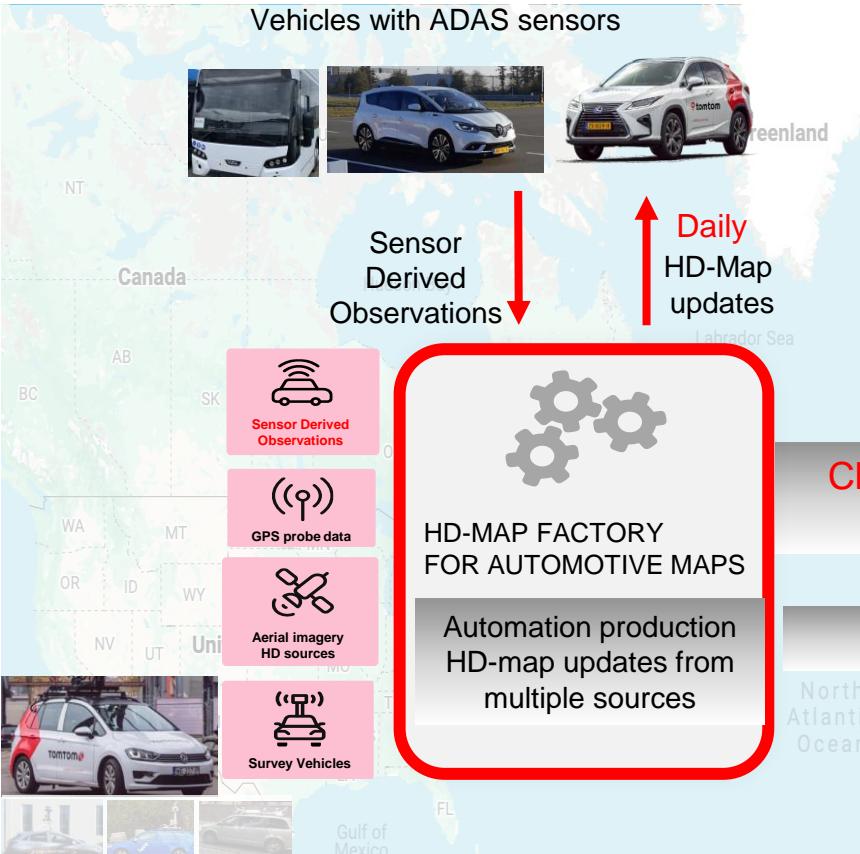
Example case:  
Data sharing concept to innovate the ADAS markets for Digital Maps



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## HD map production for ADS

Keep HD-Maps up-to-date from  
Crowdsourced Sensor-data (Camera, Radar)



Powering next generation map products by creating reliable maps from interoperable open map data between the Automotive- and Public mapping sector

Change detection Service to keep common 'ground-truth' map features up-to-date

Sharing Open Map Data via the Overture platform



## Governments digitizing Roadinfra

Producing highly-accurate map data from  
Mobile Mapping sources (Lidar)





## Collaborative Map Building

Sourcing and curating high-quality, up-to-date, and comprehensive map data from disparate sources is difficult and expensive.

Overture aims to incorporate map data from multiple sources including Overture Members, civic organizations, and open data sources.



## Global Entity Reference System

Multiple datasets reference the same real-world entities using their own conventions and vocabulary, making them difficult to merge and combine.

Overture Maps will simplify interoperability by providing a system that links entities from different data sets to the same real-world entities.



## Quality Assurance Processes

Map data is vulnerable to errors and inconsistencies.

Overture Maps data will undergo validation checks to detect map errors, breakage, and vandalism to help ensure that map data can be used in production systems.

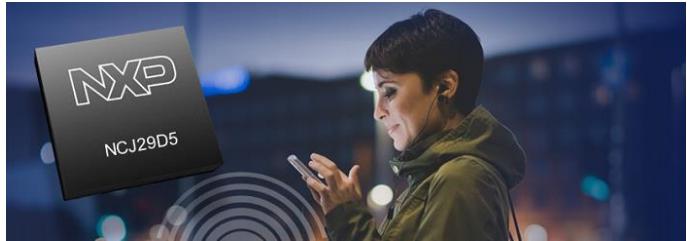


## Structured Data Schema

Open map data can lack the structure needed to easily build map products.

Overture will define and drive adoption of a common, well-structured, and documented data schema to create an easy-to-use ecosystem of map data.

# Automated vehicle functions



UWB positioning



Tele operation



Automated driving bus



Radar positioning



Digital Infra



Digital twin



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# Research with VDL CITY BUS

Automated Yard Maneuvering

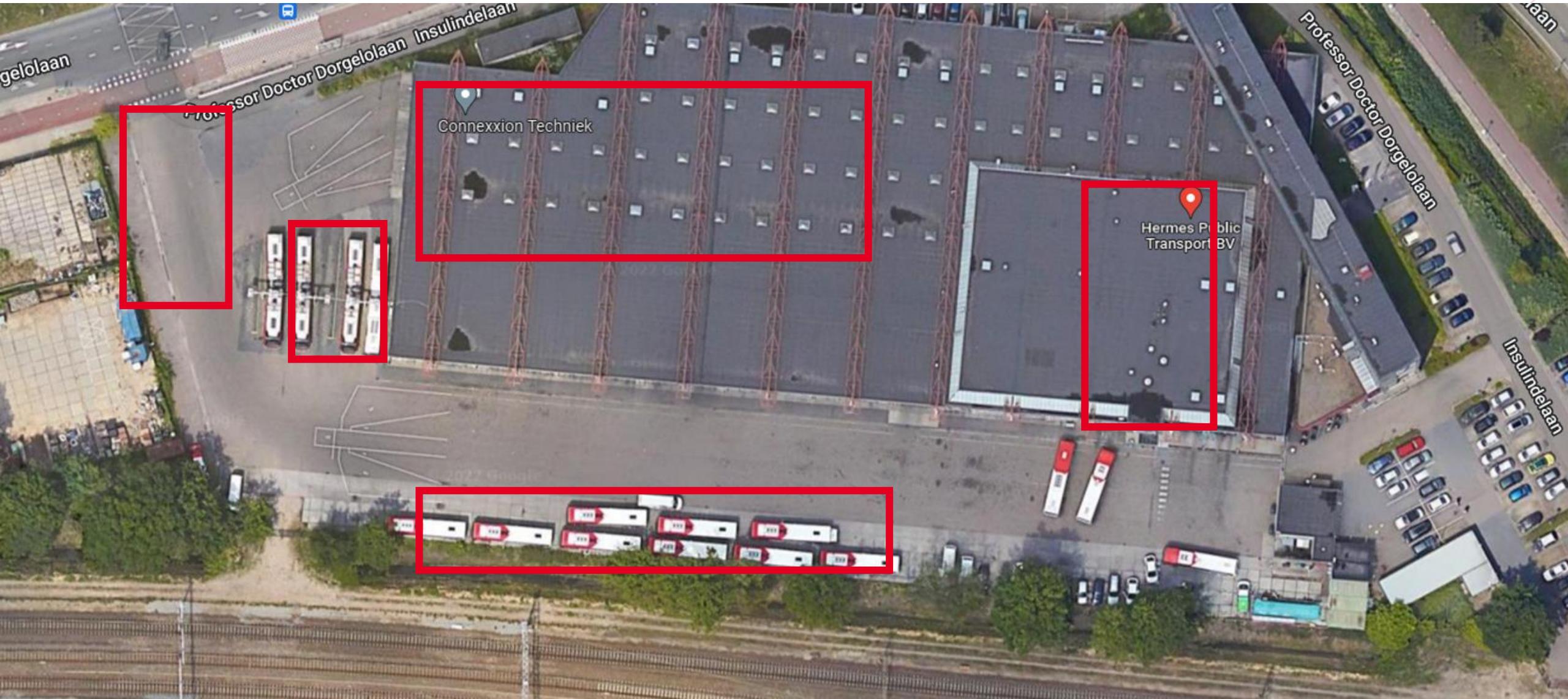
Teleoperation

Automated Halt Maneuvering

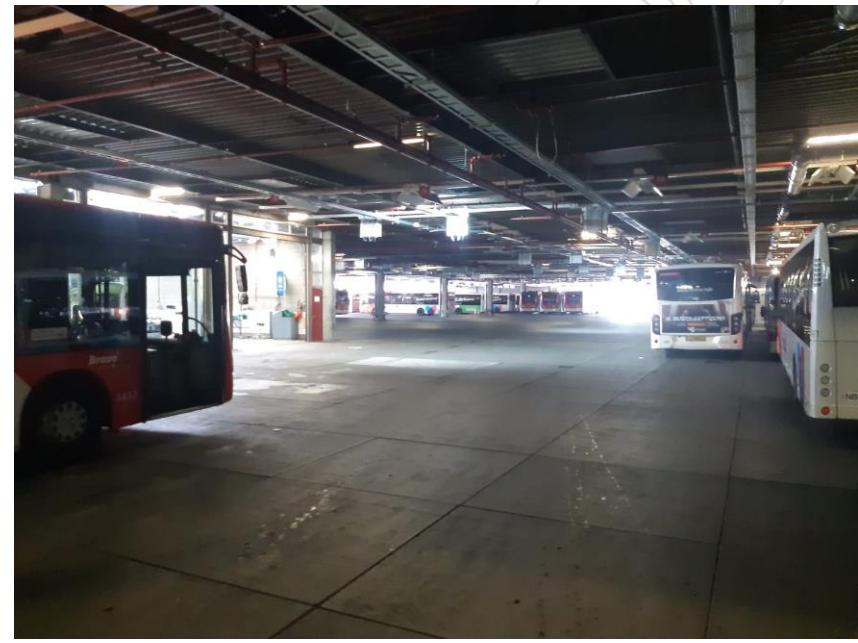
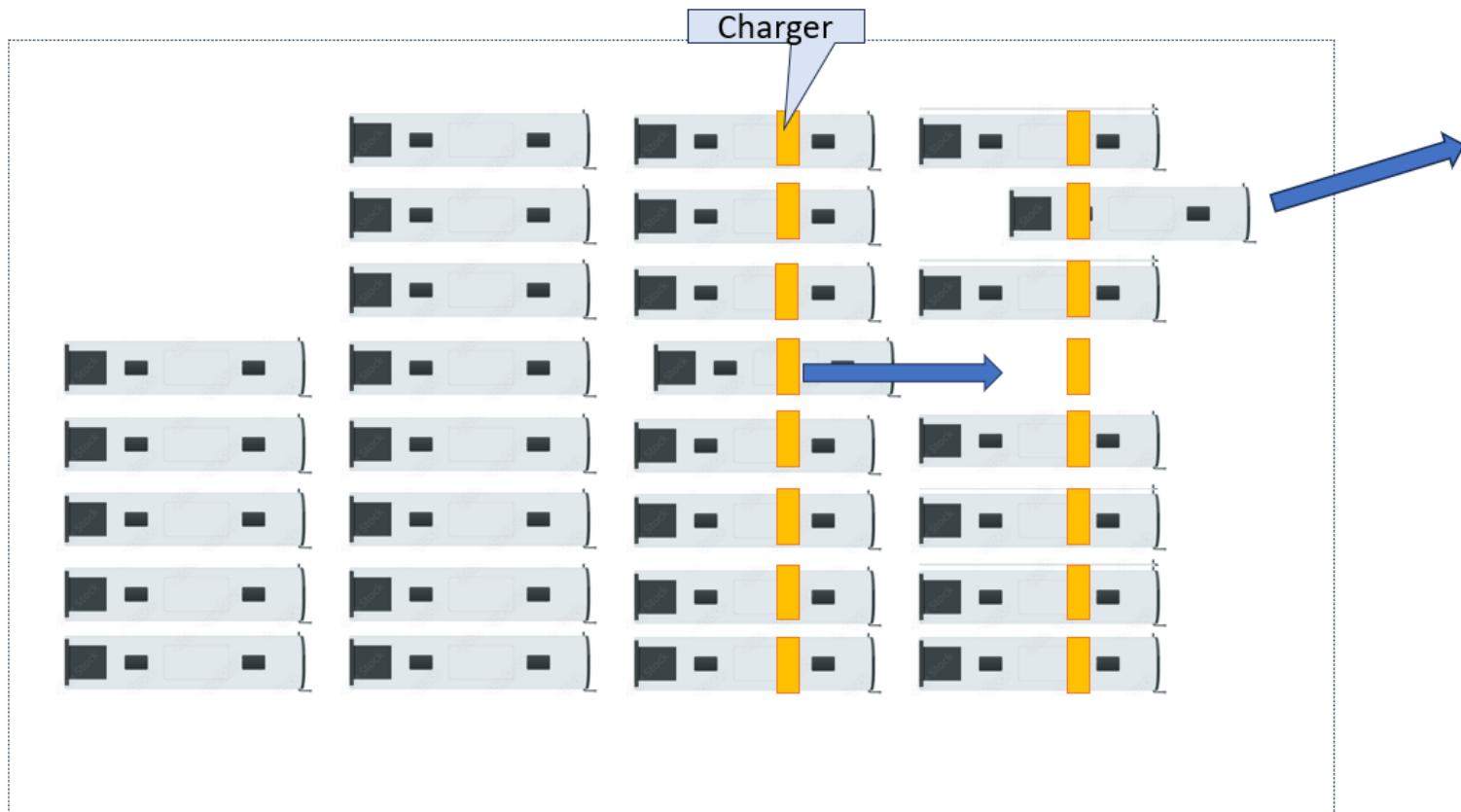
Connected platoon on  
intersection



# Automated Yard Maneuvering



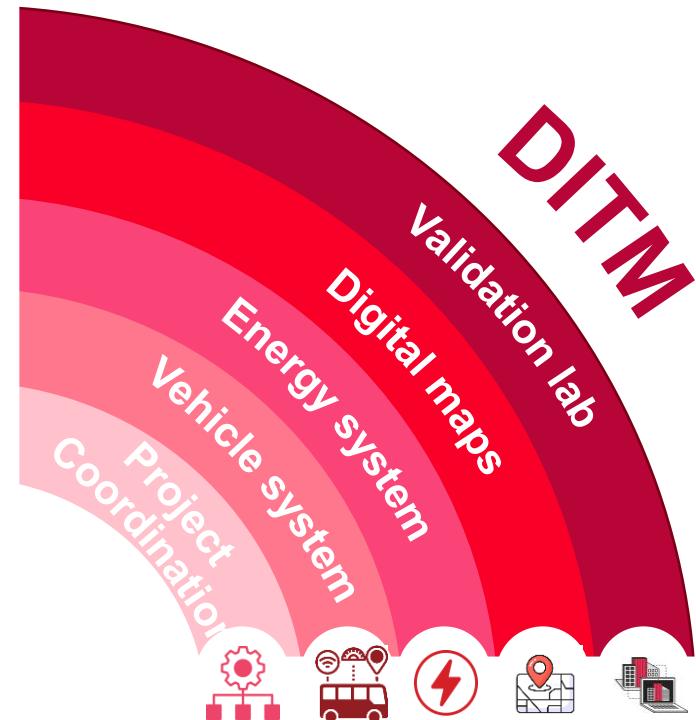
# Parking with charger



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# Theory of change



## Key enabling technologies

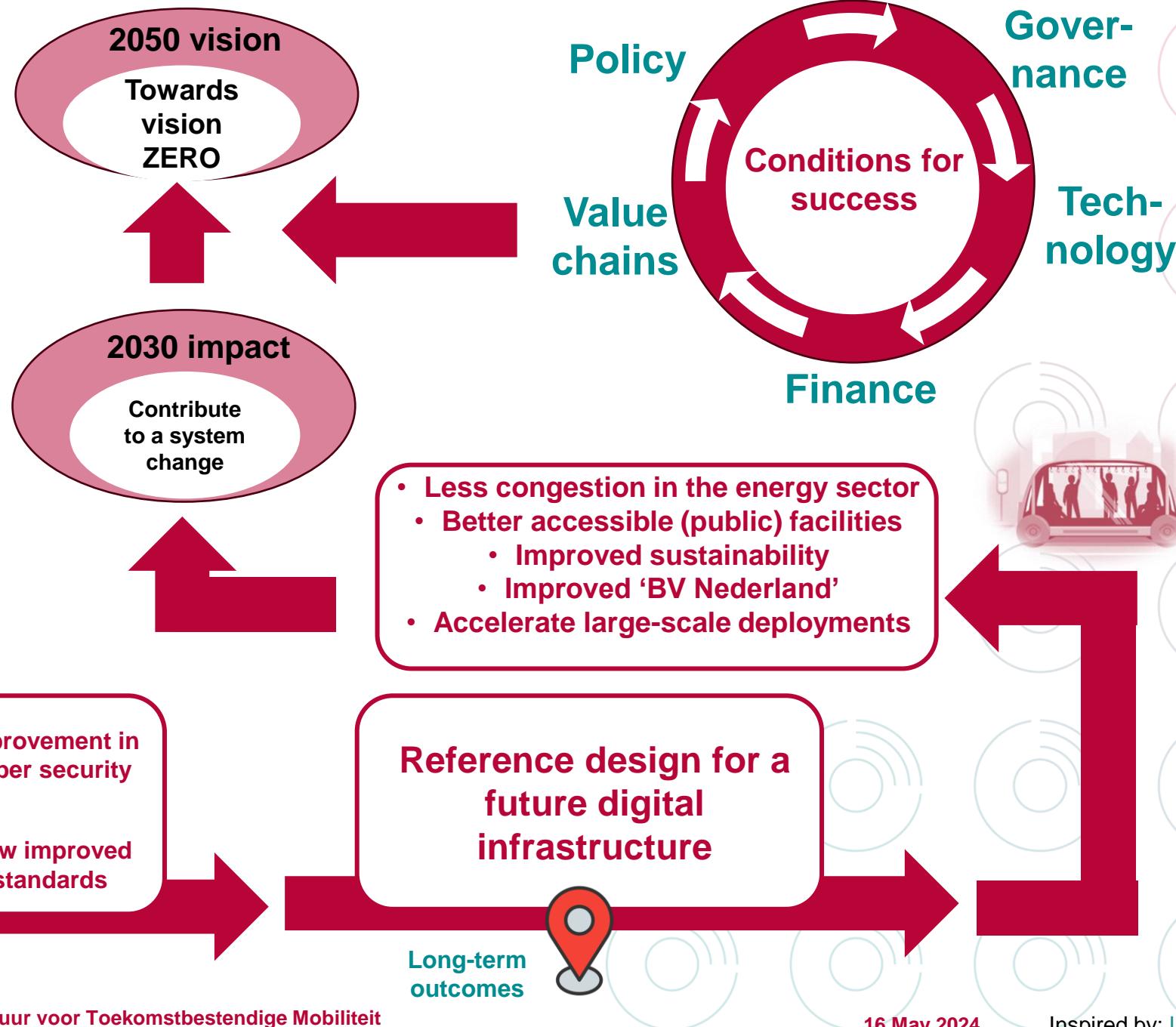
Development of self-driving functionalities  
Increased public private collaboration

Improvement in cyber security  
New improved standards

Short-term outcomes

Reference design for a future digital infrastructure

Long-term outcomes



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# DITM envisions multiple transition pathways

Optimised balancing of the electricity network through intelligent and flexible electric (vehicle) charging

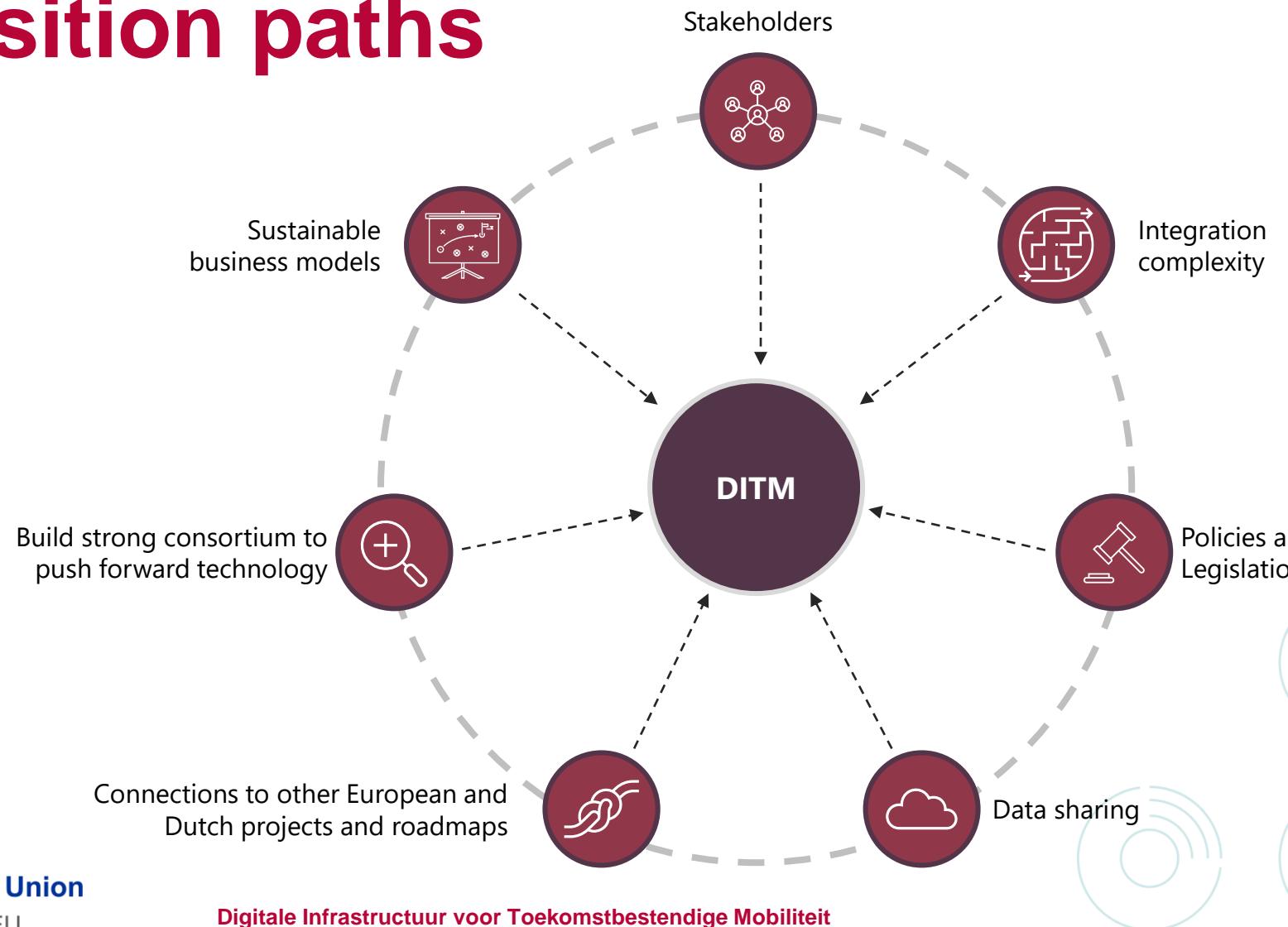
Digital maps as a key enabler for CCAM and digital twin development

Merging physical and digital worlds through Digital Twin solutions to enable acceleration of CCAM innovations

Towards a smart and responsible introduction and integration of CCAM-based solutions in The Netherlands.

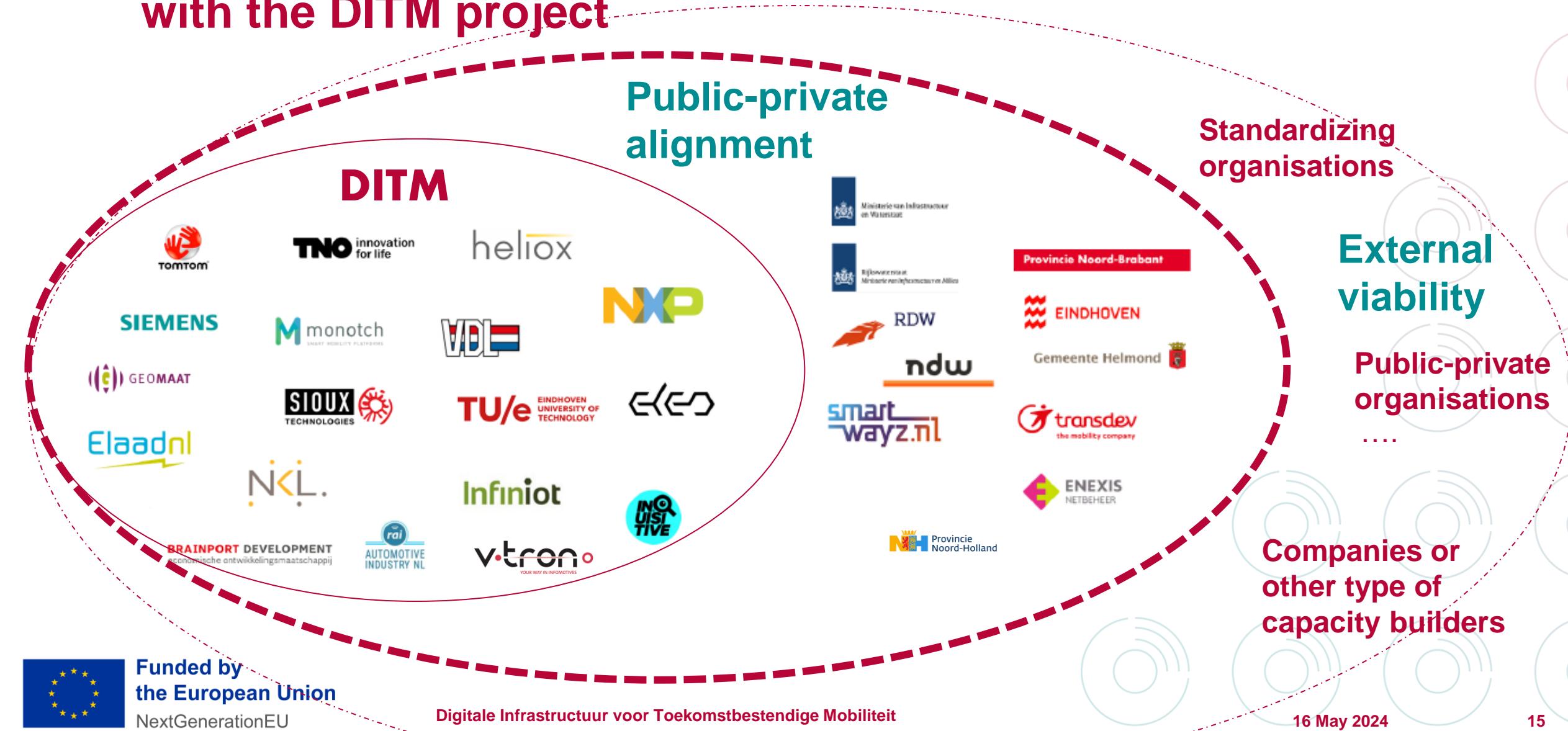


# Identifying key themes for DITM transition paths



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# Moving together and further through collaboration in & with the DITM project



# Before you leave.....

And... What do we need to achieve 'liftoff'? And how can we strengthen each other?

What do you consider as 'the' point on the horizon?

DITM envisions multiple transition pathways



# Thank you for your attention.



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